

OpenCASCADE General Transformation

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Abstract. OpenCASCADE provides a general transformation class: `gp_GTrsf`. It can be a transformation from `gp`, an affinity, or you can define your own transformation giving the matrix of transformation. The general transformation contains the vectorial part of the transformation and the translation part. A `GTrsf` transformation is only applicable to coordinates. Be careful if you apply such a transformation to all points of a geometric object, as this can change the nature of the object and thus render it incoherent. Typically a circle is transformed into an ellipse by an affinity transformation. To avoid modifying the nature of an object, use a `gp_Trsf` transformation instead, as objects of this class respect the nature of geometric objects.

Key Words. OpenCASCADE, Transformation, Affinity Transformation

1. Introduction

仿射变换（Affinity Transformation）是指线性变换后接着平移。因此，仿射变换的集合是线性变换的超集，任何线性变换都是仿射变换，但不是所有的仿射变换都是线性变换。

仿射变换的定义如下：在空间直角坐标系下，点 (x, y, z) 与点 (x', y', z') 之间的变换

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = A \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \quad A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \quad |A| \neq 0$$

称为仿射变换。如果采用特殊的齐次坐标来表达，仿射变换也可用下列形式：

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} & & b1 \\ A & & b2 \\ & & b3 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

空间仿射变换是把平面变换到平面，直线变换到直线。两个平行平面的像也是平行的。共线三点的简单比是不变量。平行六面体的体积是权为 1 的相对不变量。

OpenCASCADE 的 TKMath 库中提供了这上仿射变换类 `gp_GTrsf`，它能执行比 `gp_Trsf` 更通用的变换。对于 TopoDS_Shape，OpenCASCADE 分别提供了如下两个类进行变换：

- ❖ `BRepBuilderAPI_GTransform`
- ❖ `BRepBuilderAPI_Transform`

本文在 OpenCASCADE Draw Test Harness 中给出这两个类实现变换的结果。如果不想改变几何的特性，只想改变模型的位置或朝向，建议采用 `BRepBuilderAPI_Transform`。

2. BRepBuilderAPI_Transform

OpenCASCADE 中使用算法 BRepBuilderAPI_Transform 来实现：平移、旋转、缩放及镜像变换。在 Draw Test Harness 中实现的函数代码如下所示：

```
static Standard_Integer transform(Draw_Interpretor& di, Standard_Integer n, const
char** a)
{
    if (n <= 1) return 1;

    gp_Trsf T;
    Standard_Integer last = n;
    const char* aName = a[0];

    Standard_Boolean isBasic = Standard_False;

    if (!strcmp(aName, "reset")) {
    }
    else {
        isBasic = (aName[0] == 'b');
        aName++;

        if (!strcmp(aName, "move")) {
            if (n < 3) return 1;
            TopoDS_Shape SL = DBRep::Get(a[n-1]);
            if (SL.IsNull()) return 0;
            T = SL.Location().Transformation();
            last = n-1;
        }
        else if (!strcmp(aName, "translate")) {
            if (n < 5) return 1;

T.SetTranslation(gp_Vec(Draw::Atof(a[n-3]), Draw::Atof(a[n-2]), Draw::Atof(a[n-1])));
            last = n-3;
        }
        else if (!strcmp(aName, "rotate")) {
            if (n < 9) return 1;

T.SetRotation(gp_Ax1(gp_Pnt(Draw::Atof(a[n-7]), Draw::Atof(a[n-6]), Draw::Atof(a[n-5])),

gp_Vec(Draw::Atof(a[n-4]), Draw::Atof(a[n-3]), Draw::Atof(a[n-2]))),
                Draw::Atof(a[n-1])* (M_PI / 180.0));
            last = n-7;
        }
        else if (!strcmp(aName, "mirror")) {
            if (n < 8) return 1;

T.SetMirror(gp_Ax2(gp_Pnt(Draw::Atof(a[n-6]), Draw::Atof(a[n-5]), Draw::Atof(a[n-4])),
```

```

gp_Vec(Draw::Atof(a[n-3]), Draw::Atof(a[n-2]), Draw::Atof(a[n-1]))));
    last = n-6;
}
else if (!strcmp(aName, "scale")) {
    if (n < 6) return 1;

T.setScale(gp_Pnt(Draw::Atof(a[n-4]), Draw::Atof(a[n-3]), Draw::Atof(a[n-2])), Dr
aw::Atof(a[n-1]));
    last = n-4;
}
}

if (T.Form() == gp_Identity || isBasic) {
    TopLoc_Location L(T);
    for (Standard_Integer i = 1; i < last; i++) {
        TopoDS_Shape S = DBRep::Get(a[i]);
        if (S.IsNull())
            di << a[i] << " is not a valid shape\n";
        else
            DBRep::Set(a[i], S.Located(L));
    }
}
else {
    BRepBuilderAPI_Transform trf(T);
    for (Standard_Integer i = 1; i < last; i++) {
        TopoDS_Shape S = DBRep::Get(a[i]);
        if (S.IsNull()) {
            di << a[i] << " is not a valid shape\n";
        }
        else {
            trf.Perform(S);
            if (!trf.IsDone())
                return 1;
            DBRep::Set(a[i], trf.Shape());
        }
    }
}
return 0;
}

```

下面给出应用 Tcl 脚本来实现这些变换的例子：

```

# make rotated copies of a sphere in between two cylinders
# create a file source toto.tcl
# toto.tcl code:
pload ALL

#create a sphere
psphere s 3
ttranslate s 25 0 12.

for {set i 0} {$i < 360} {incr i 20} {

```

```
copy s s$i
trotate s$i 0 0 0 0 1 $i

vdisplay s$i
}

# create two cylinders
pcylinder c1 30 5
copy c1 c2
ttranslate c2 0 0 20
vdisplay c1 c2 s
```

脚本运行效果如下图所示：

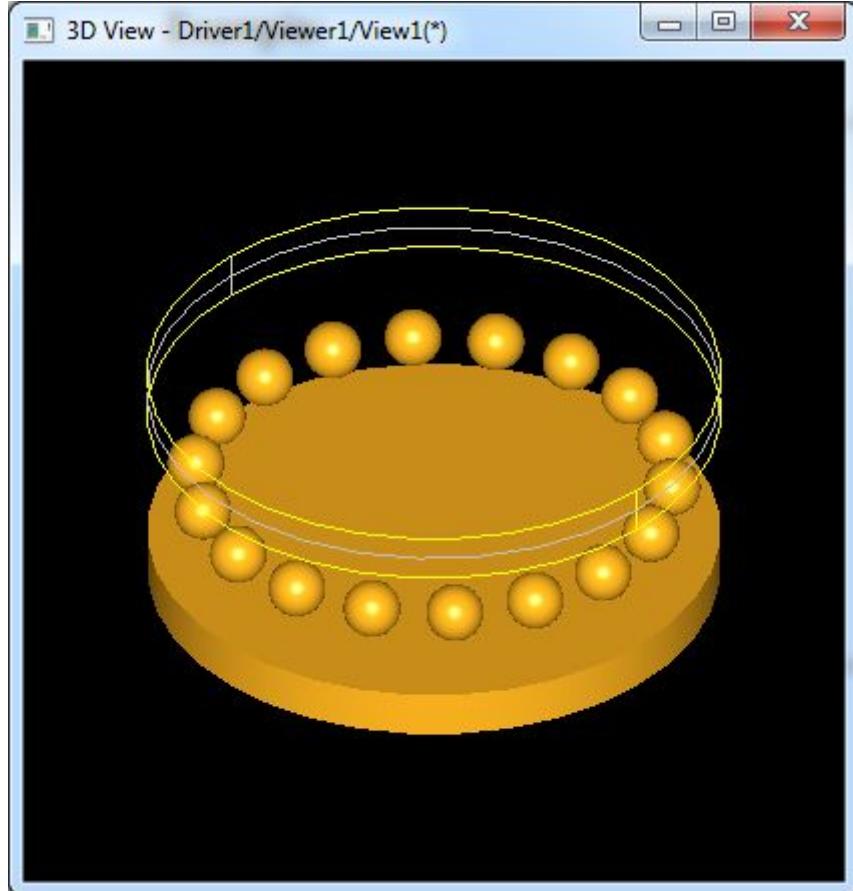


Figure 2.1 Transform Tcl demo

从 Draw 中实现的函数来看，移动、旋转及缩放变换都是使用类 BRepBuilderAPI_Transformation 来实现。Tcl 脚本中先创建出一个球体，再平移后，复制 13 份，最后又创建出两个圆柱体。如果要对 TopoDS_Shape 进行变换且不改变其中的几何性质，建议都使用这个类来完成。

3. BRepBuilderAPI_GTransform

在 OpenCASCADE 也可使用仿射变换 BRepBuilderAPI_GTransform 来对形状实现上述变换操作，还可提供变形的变换，因此仿射变换是更一般的变换方法。在 Draw 中实现的函数代码如下所示：

```
///-----
// gtransform
//-----

static Standard_Integer deform(Draw_Interpreter& di, Standard_Integer n, const
char** a)
{
    if (n <= 1) return 1;

    Standard_Integer last = n;

    gp_Trsf T;
    gp_GTrsf GT(T);

    //                                     gp_Mat
rot(Draw::Atof(a[last-3]), 0, 0, 0, Draw::Atof(a[last-2]), 0, 0, 0, Draw::Atof(a[last-1])
));
    gp_Mat rot(Draw::Atof(a[3]), 0, 0, 0, Draw::Atof(a[4]), 0, 0, 0, Draw::Atof(a[5]));
    GT.SetVectorialPart(rot);
    last -= 3;
    BRepBuilderAPI_GTransform gtrf(GT);
    BRepBuilderAPI_NurbsConvert nbscv;
    // for (Standard_Integer i = 1; i < last; i++) {
    //   TopoDS_Shape S = DBRep::Get(a[i]);
    TopoDS_Shape S = DBRep::Get(a[2]);
    if (S.IsNull()) {
        //cout << a[2] << " is not a valid shape" << endl;
        di << a[2] << " is not a valid shape" << "\n";
    }
    else {
        gtrf.Perform(S);
        if (gtrf.IsDone()){
            DBRep::Set(a[1], gtrf.Shape());
        }
        else {
            return 1;
        }
    }
}

return 0;
}
```

根据仿射变换的定义，给定一个球面的数学表达式：

$$x^2 + y^2 + z^2 = 1$$

应用如下的仿射变换，将会得到一个椭球面：

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} a & 0 & 0 & b_1 \\ 0 & b & 0 & b_2 \\ 0 & 0 & c & b_3 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} \quad abc \neq 0$$

由变换公式解得：

$$\begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} 1/a & 0 & 0 & 0 \\ 0 & 1/b & 0 & 0 \\ 0 & 0 & 1/c & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix}$$

将它代入球面方程得到：

$$\frac{x'^2}{a^2} + \frac{y'^2}{b^2} + \frac{z'^2}{c^2} = 1$$

在 Draw 中使用 BRepBuilderAPI_GTransform 变换得到如下图所示：

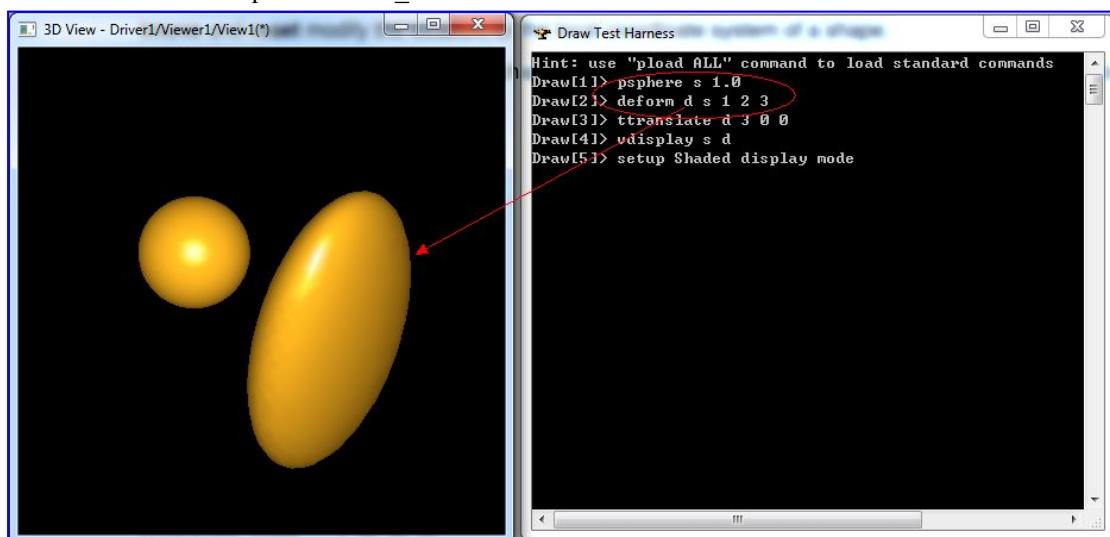


Figure 3.1 Shape Deformation

关于仿射变换有个重要定理：一般仿射变换是正交变换、沿着三个互相正交方向的压缩或放大和平移这三者的乘积。上述命令的实现代码就是设置了仿射矩阵中的 a, b 和 c 值，从而达到对模型变形的效果。

4. Conclusion

在三维建模软件中经常需要对模型的位置和其朝向进行变换，如果不改变模型中的几何特性，在 OpenCASCADE 中建议使用类 BRepBuilderAPI_Transform 来实现。如果需要对模型进行更通用的变换即仿射变换，可以使用类 BRepBuilderAPI_GTransform 来实现。使用此类后，会改变模型中的几何特性，必须谨慎使用。

5. References

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2. 苏步表, 华宣积. 应用几何教程. 复旦大学出版社. 2012
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